CBSE Class-12 Physics Quick Revision Notes Chapter-07: Alternating Current

• Alternating Current:

The current whose magnitude changes with time and direction reverses periodically is called alternating current. a) Alternating emf E and current I at any time am given by:

$$E = E_0 \sin \omega t$$

Where
$$E_0 = NBA\omega$$

$$I = I_0 \sin(\omega t - \phi)$$

Where
$$I_0 = \frac{NBA\omega}{R}$$

$$\omega = 2\pi n = \frac{2\pi}{T}$$

Where T is the time period.

Values of Alternating Current and Voltage

a) Instantaneous value:

It is the value of alternating current and voltage at an instant t.

b) Peak value:

Maximum values of voltage E_0 and current I_0 in a cycle are called peak values.

c) Mean value:

For complete cycle,

$$\langle E \rangle = \frac{1}{T} \int_{0}^{T} E dt = 0$$

$$\langle I \rangle = \frac{1}{T} \int_{0}^{T} I dt = 0$$

Mean value for half cycle: $E_{mean} = \frac{2E_0}{\pi}$

d) Root – mean- square (rms) value:

$$E_{rms} = (\langle E^2 \rangle)^{1/2} = \frac{E_0}{\sqrt{2}} = 0.707 E_0 = 70.7\% E_0$$

$$I_{rms} = (\langle I^2 \rangle)^{1/2} = \frac{I_0}{\sqrt{2}} = 0.707I_0 = 70.7\%I_0$$

RMS values are also called apparent or effective values.

- Phase difference Between the EMF (Voltage) and the Current in an AC Circuit
 - a) For pure resistance:

The voltage and the current are in same phase i.e. phase difference $\phi = 0$

b) For pure inductance:

The voltage is ahead of current by $\frac{\pi}{2}$ i.e. phase difference $\phi = +\frac{\pi}{2}$.

c) For pure capacitance:

The voltage lags behind the current by $\frac{\pi}{2}$ i.e. phase difference $\phi = -\frac{\pi}{2}$

Reactance:

Reactance

a)
$$X = \frac{E}{I} = \frac{E_0}{I_0} = \frac{E_{rms}}{I_{rms}} \pm \pi / 2$$

b) Inductive reactance
$$X_{L} = \omega L = 2\pi nL$$

Capacitive reactance

c)
$$X_C = \frac{1}{\omega C} = \frac{1}{2\pi nC}$$

Impedance:

Impedance is defined as,

$$Z = \frac{E}{I} = \frac{E_0}{I_0} = \frac{E_{rms}}{I_{rms}} \phi$$

Where ϕ is the phase difference of the voltage E relative to the current I.

a) For L – R series circuit:

$$Z_{RL} = \sqrt{R^2 + X_L^2} = \sqrt{R^2 + \omega L^2}$$

$$\tan \phi = \left(\frac{\omega L}{R}\right) or \phi = \tan^{-1} \left(\frac{\omega L}{R}\right)$$

b) For R – C series circuit:

$$Z_{RC} = \sqrt{R^2 + X_C^2} = \sqrt{R^2 + \left(\frac{1}{\omega C}\right)^2}$$

$$\tan \phi = \frac{1}{\omega CR} \text{ Or } \phi = \tan^{-1} \left(\frac{1}{\omega CR} \right)$$

c) For L – C series circuit:

$$Z_{LCR} = \sqrt{R^2 + (X_L - X_C)^2}$$

$$= \sqrt{R^2 + \left(\omega L - \frac{1}{\omega C}\right)^2}$$

$$\tan \phi = \frac{\left(\omega L - \frac{1}{\omega C}\right)}{R} \text{ Or } \phi = \tan^{-1} \left(\frac{\omega L - \frac{1}{\omega C}}{R}\right)$$

Conductance:

Reciprocal of resistance is called conductance.

$$G = \frac{1}{R}mho$$

• Power in and AC Circuit:

a) Electric power = (current in circuit) x (voltage in circuit)

$$P = IE$$

b) Instantaneous power:

$$P_{inst} = E_{inst} \times I_{inst}$$

c) Average power:

$$P_{av} = \frac{1}{2} E_0 I_0 \cos \phi = E_{rms} I_{rms} \cos \phi$$

d) Virtual power (apparent power):

$$= \frac{1}{2} E_0 I_0 = E_{rms} I_{rms}$$

• Power Factor:

a) Power factor

$$\cos\phi = \frac{P_{av}}{P_{v}} = \frac{R}{Z}$$

b) For pure inductance

Power factor, $\cos \phi = 1$

c) For pure capacitance

Power factor, $\cos \phi = 0$

d) For LCR circuit

Power factor,
$$\cos \phi = \frac{R}{\sqrt{R^2 + \left(\omega L - \frac{1}{\omega C}\right)^2}}$$

$$X = \left(\omega L - \frac{1}{\omega C}\right)$$

• Wattless Current:

The component of current differing in phase by $\frac{\pi}{2}$ relative to the voltage, is called wattles current.

• The rms value of wattless current:

$$= \frac{I_0}{\sqrt{2}} \sin \phi$$

$$= I_{rms} \sin \phi = \frac{I_0}{\sqrt{2}} \left(\frac{X}{Z}\right)$$

• Choke Coil:

- a) An inductive coil used for controlling alternating current whose self- inductance is high and resistance in negligible, is called choke coil.
- b) The power factor of this coil is approximately zero.

• Series Resonant Circuit

- a) When the inductive reactance (XL) becomes equal to the capacitive reactance (XC) in the circuit, the total impedance becomes purely resistive (Z=R).
- b) In this state, the voltage and current are in same phase ($\phi = 0$), the current and power are maximum and impedance is minimum. This state is called resonance.
- c) At resonance,

$$\omega_r L = \frac{1}{\omega_r C}$$

Hence, resonance frequency is,

$$f_r = \frac{1}{2\pi\sqrt{LC}}$$

d) In resonance, the power factor of the circuit is one.

• Half - Power Frequencies:

Those frequencies f_1 and f_2 at which the power is half of the maximum power (power at resonance), i.e., f_1 and f_2 are called half – power frequencies.

$$P = \frac{1}{2} P_{\text{max}}$$

$$I = \frac{I_{\text{max}}}{\sqrt{2}}$$

$$\therefore P = \frac{P_{\text{max}}}{2}$$

• Band - Width:

- a) The frequency interval between half power frequencies is called band width.
 - \therefore Bandwidth $\Delta f = f_2 f_1$
- b) For a series LCR resonant circuit,

$$\Delta f = \frac{1}{2\pi} \frac{R}{L}$$

• Quality Factor (Q):

$$Q = 2\pi \times \frac{\text{Maximum energy stored}}{\text{Energy dissipated per cycle}}$$
$$= \frac{2\pi}{T} \times \frac{\text{Maximum energy stored}}{\text{Mean power dissipated}}$$

Or

$$Q = \frac{\omega_r L}{R} = \frac{1}{\omega_r CR} = \frac{f_r}{(f_2 - f_1)} = \frac{f_r}{\Delta f}$$